



# A new four-step explicit method with vanished phase-lag and its derivatives for the numerical solution of radial Schrödinger equation

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## Abstract

In this paper, we present a new method for the numerical solution of the time-independent Schrödinger equation for one spatial dimension and related problems. A technique, based on the phase-lag and its derivatives, is used, in order to calculate the parameters of the new Numerov-type algorithm. We illustrate the accuracy and computational efficiency of the new developed method via numerical examples.

**Keywords:** Multistep methods, Oscillating solution, Phase-lag, Initial value problems, Schrödinger equation

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## 1 Introduction

The radial time- independent Shorödinger equation can be written as

$$y''(x) = \left( \frac{l(l+1)}{x^2} + V(x) - E \right) y(x), \quad (1)$$

where  $\frac{l(l+1)}{x^2}$  is the centrifugal potential,  $V(x)$  is the potential,  $E$  is the energy and  $W(x) = \frac{l(l+1)}{x^2} + V(x)$  is the effective potential. It is valid that  $\lim_{x \rightarrow \infty} V(x) = 0$  and therefore  $\lim_{x \rightarrow \infty} W(x) = 0$ . We consider  $E > 0$  and divide  $[0, \infty)$  into subintervals  $[a_i, b_i]$  so that  $W(x)$  is a constant with value  $\overline{W}$ . After this the problem (1) can be expressed by the approximation:  $y''_i = (\overline{W} - E)y_i$ , whose theoretical solution is  $y_i = A_i \exp(\sqrt{\overline{W} - E}x) + B_i \exp(\sqrt{\overline{W} - E}x)$ , where  $A_i, B_i \in \mathbb{R}$ . Many numerical methods have been developed for the efficient solution of the Schrödinger equation and related problems [1 - 5].

## 2 Phase-lag analysis of symmetric multistep methods

For the numerical solution of the initial value problem

$$y'' = f(x, y), \quad y(x_0) = y_0, \quad y'(x_0) = y'_0, \quad (2)$$

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