

46th Annual Iranian Mathematics Conference 25-28 August 2015 Yazd University



Classification pseudosymmetric (κ, μ) -contact metric manifolds

Classification pseudosymmetric (κ, μ) -contact metric manifolds

Nasrin Malekzadeh^{*} Azarbaijan Shahid Madani University Esmaiel Abedi Azarbaijan Shahid Madani University

Abstract

This paper deals with a classification of the pseudosymmetric contact metric manifolds under the condition that the characteristic vector field ξ belong to the (κ, μ) nullity distribution in the R. Deszcz sense.

Keywords: Pseudosymmetric, Semisymmetric, (κ, μ) -nullity distribution, Contact manifold Mathematics Subject Classification [2010]: 53D10, 53C35

1 Introduction

Chaki [3]and Deszcz [4] introduced two different concept of a pseudosymmetric manifold. In both senses various properties of pseudosymmetric manifolds have been studied. We shall study properties of pseudosymmetric manifolds in the Deszcz sense. A Riemannian manifold is called semisymmetric if R(X,Y). R = 0. Deszcz [4] generalized the concept of semisymmetry and introduced pseudosymmetric manifolds. Let (M^n,g) , $n \ge 3$ be a Riemannian manifold. Let ∇ and R denote the Levi-Civita connection and the curvature tensor of (M,g). We define endomorphism $X \wedge Y$ by

$$(X \wedge Y)Z = g(Y, Z)X - g(X, Z)Y.$$
(1)

For a (0, k)-tensor field T, the (0, k+2) tensor fields R.T and Q(g, T) are defined by [4]

$$(R.T)(X_1, ..., X_k; X, Y) = (R(X, Y).T)(X_1, ..., X_k)$$

= $-T(R(X, Y)X_1, X_2, ..., X_k) - ... - T(X_1, ..., X_{k-1}, R(X, Y)X_k),$ (2)

$$Q(g,T)(X_1,...,X_k;X,Y) = ((X \land Y).T)(X_1,...,X_k) = -T((X \land Y)X_1,X_2,...,X_k) - ... - T(X_1,...,X_{k-1},(X \land Y)X_k),$$
(3)

A Riemannian manifold M is said to be pseudosymmetric if the tensors R.R and Q(g,R) are linearly dependent at every point of M, i.e. $R.R = L_RQ(g,R)$. This is equivalent to

$$(R(X,Y).R)(U,V,W) = L_R[((X \land Y).R)(U,V,W)]$$
(4)

holding on the set $U_R = \{x \in M : Q(g, R) \neq 0 \text{ at } x\}$, where L_R is some function on U_R [4]. The manifold M is called a pseudosymmetric of constant type if L is constant. Particularly if $L_R = 0$ then M is a semisymmetric manifold. Papantoniou classified semisymmetric (κ, μ) -contact metric manifolds [5]. As a generalization, in this paper, we study pseudosymmetric (κ, μ) -contact metric manifolds.

^{*}Speaker