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On the flag curvature of bi-invariant Randers metrics

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Abstract

In this paper we study the flag curvature of bi-invariant Randers metrics. We first correct a minor error which occurred for the flag curvature formula of a bi-invariant Randers metric. Then we improve this formula on a connected Lie group G and as an application we explicitly give this formula for the Lie groups SO(4) and U(3) which show that these spaces are of non-negative flag curvatures. Some results on the flag curvature formula of a naturally reductive Randers metric are also improved.

Keywords: Flag curvature, Bi-invariant Randers metrics, Connected Lie groups Mathematics Subject Classification [2010]: 53C60, 53C30.

1 Introduction

The study of invariant structures on Lie groups and homogeneous manifolds is an interesting subject in differential geometry. In the last decade a generalization of these concepts from the Riemannian geometry into the Finsler geometry, specially Randers metrics have been done [1, 2, 3, 4, 5, 6]. One of these invariant structures are bi-invariant metrics and the study of the flag curvature of bi-invariant metrics as a generalization of sectional curvatures in the Riemannian geometry has absorbed a special attention of the mathematics scientists. In particular in [6] an explicit formula for the flag curvature of bi-invariant Randers metrics is given which has a minor error. Our aim in this paper is to correct this formula. We also improve this formula and apply it for calculating the flag curvature of the compact Lie groups SO(4) and U(3). Some interesting results for the flag curvature of naturally reductive are also proved.

2 The flag curvature of a bi-invariant Randers metric

The following formula

$$K(P,y) = \frac{\langle [y, [u, y]], V \rangle_0 \cdot \langle V, u \rangle_0 + \langle [y, [u, y]], u \rangle_0 (1 + \langle V, y \rangle_0)}{4(1 + \langle V, y \rangle_0)^2(1 - \langle V, y \rangle_0)}, \quad (1)$$

is given in [6] for the flag curvature of a Randers metric which is defined by a bi-invariant Riemannian metric g_0 and a left-invariant vector field V which is parallel with respect to g_0 . In the correct way it can be written as

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