

Coupling from the past with randomized quasi-Monte Carlo

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Abstract

The coupling-from-the-past (CFTP) algorithm of Propp and Wilson permits one to sample exactly from the stationary distribution of an ergodic Markov chain. By using it n times independently, we obtain an independent sample from that distribution. A more representative sample can be obtained by creating negative dependence between these n replicates; other authors have already proposed to do this via antithetic variates, Latin hypercube sampling, and randomized quasi-Monte Carlo (RQMC). We study a new, often more effective, way of combining CFTP with RQMC, based on the array-RQMC algorithm. We provide numerical illustrations for Markov chains with both finite and continuous state spaces, and compare with the RQMC combinations proposed earlier.

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1. Introduction

The Monte Carlo (MC) method is a key tool for estimating mathematical expectations of the form

$$\mu = \int_{\mathcal{S}} c(x) d\pi(x), \quad (1)$$

where π is a probability measure defined over some measurable space $(\mathcal{S}, \mathcal{F})$, and $c : \mathcal{S} \rightarrow \mathbb{R}$ is a measurable cost (or reward) function. If we know how to sample exactly and efficiently from the measure π , then we can sample n independent realizations of a random variable X from this measure, compute $c(X)$ for each of them, and take the average. This is the Monte Carlo method.

However, there are many practical situations where we have no direct way of sampling exactly from π . An important type of setting where this occurs naturally is when we want to estimate the steady-state average cost per step for a system whose evolution is modeled by an ergodic Markov chain $\{X_j, j \geq 0\}$, often with large state space \mathcal{S} and complicated dynamics; see [10,12] and [1, Chapter IV], for example. Typically, in this case, we have little a priori clue of how π might look like but we can easily simulate the Markov chain. For example, the Markov chain might represent the day-to-day evolution of an inventory system whose state on day j is X_j , $c(X_j)$ is the cost for that day given X_j (we assume that X_j contains enough information for the model to be Markovian and for the cost to be

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