Temporal-difference search in computer Go

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Abstract Temporal-difference learning is one of the most successful and broadly applied solutions to the reinforcement learning problem; it has been used to achieve master-level play in chess, checkers and backgammon. The key idea is to update a value function from episodes of real experience, by bootstrapping from future value estimates, and using value function approximation to generalise between related states. Monte-Carlo tree search is a recent algorithm for high-performance search, which has been used to achieve masterlevel play in Go. The key idea is to use the mean outcome of simulated episodes of experience to evaluate each state in a search tree. We introduce a new approach to highperformance search in Markov decision processes and two-player games. Our method, temporal-difference search, combines temporal-difference learning with simulation-based search. Like Monte-Carlo tree search, the value function is updated from simulated experience; but like temporal-difference learning, it uses value function approximation and bootstrapping to efficiently generalise between related states. We apply temporal-difference search to the game of 9×9 Go, using a million binary features matching simple patterns of stones. Without any explicit search tree, our approach outperformed an unenhanced Monte-Carlo tree search with the same number of simulations. When combined with a simple alpha-beta search, our program also outperformed all traditional (pre-Monte-Carlo) search and machine learning programs on the 9×9 Computer Go Server.

Keywords Reinforcement learning · Temporal-difference learning · Monte-Carlo search · Simulation based search · Computer Go

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